Features

- Safe and easy flight operations	- Live video downlink to the ground
– Emergency FailSafe recovery	 – GPS flight assistance and auto-pilot
– Flight data recording	 Automatic take-off and landing
 Redundant flight control system 	– Waypoints flying
 Redundant flight control power 	– Relative Waypoints
- Redundant Sensors for accuracy &	– Click and Fly: single point navigation
failsafe	– Coming Home
- Multiple Fail Safe positions	– Position Hold
– Geo-Fencing	– Altitude Hold
- Showing limits of the flight envelope	– Dynamic Position Hold
– Advanced GPS	
– Live Track on PC or tablet	- Position Save
Automatic company companyation	 Long distance Way points flying
 Automatic camera compensation 	– Advanced 32-bit ARM central
– 4 Mega Pixel Camera	processors
 Display trigger points on a map 	– State-of-the-art motors
	– Long flight times

<u>Specifications</u> (2200mm Octocopter)

- Flight time: 65 minutes
- Flight time with 7Kg payload & Battery: 40 minutes
- Range: 8 Km (LoS)
- Max Speed: 60Km/h
- Max payload: 10 Kg (Apart from Battery Weight)
- Max Altitude: user adjustable up to 1000m
- Motors: 170kV
- Propellers: 29" Diameter 9.5" pitch (Quick Attach Detach), Carbon Fiber Flight Controller: ARM based Pixhawk 2.1
- Communication: 5.8G Video Transmission (Digital) (10Km Range LoS) , 2.4G
- Transmitter Control, 433Mhz/915Mhz/RF900 Telemetry
- Weight: 8Kg without Battery, Camera, Gimbal & Payload
- Flight Battery: 46,000 Mah 22.2v Rechargeable Lithium Ion Battery (4.2 Kg)
- Gimbal: 3-axis stabilization with Pan Tilt control
- Camera: 2.0MP Camera, 33x Optical Zoom, 1920×1080 Resolution, WDR, DNR, High

Speed Focus, IP Camera